Threading Algorithm

* Start both threads
  + One runs Q-Learning
  + Other runs constant listener
* Let both threads run infinitely
* If at any point in time the listener thread detects the Word “Cozmo”
  + Check if speech contains “Stop”
    - If it does then terminate the Q-Learning thread
    - Make the robot go idle
  + Else if speech contains “move”
    - Then check the current state and move to the other one